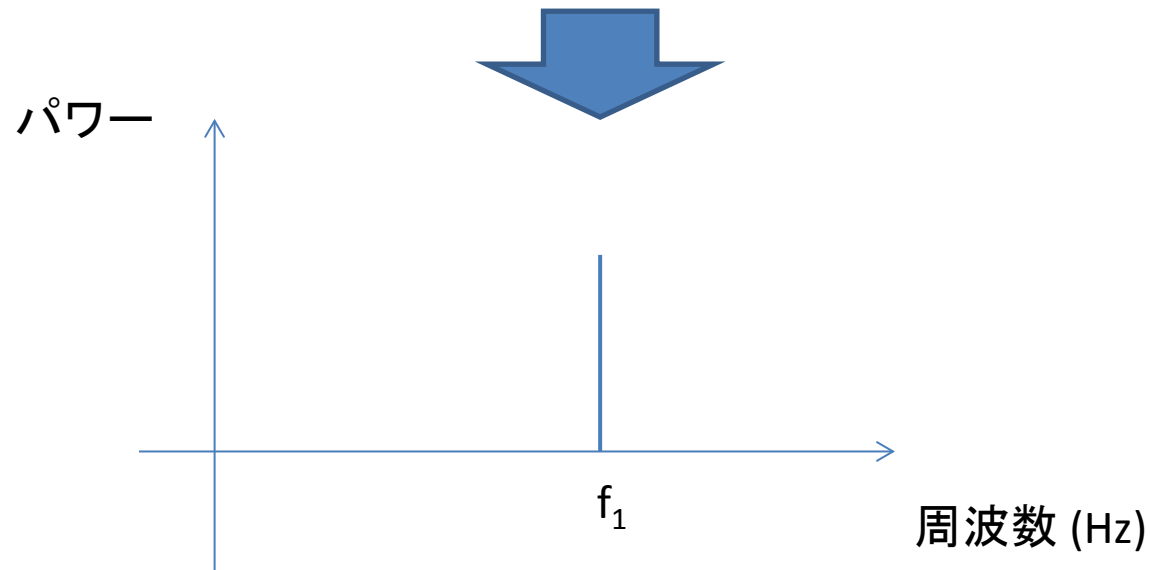


# フーリエ変換

# フーリエ変換

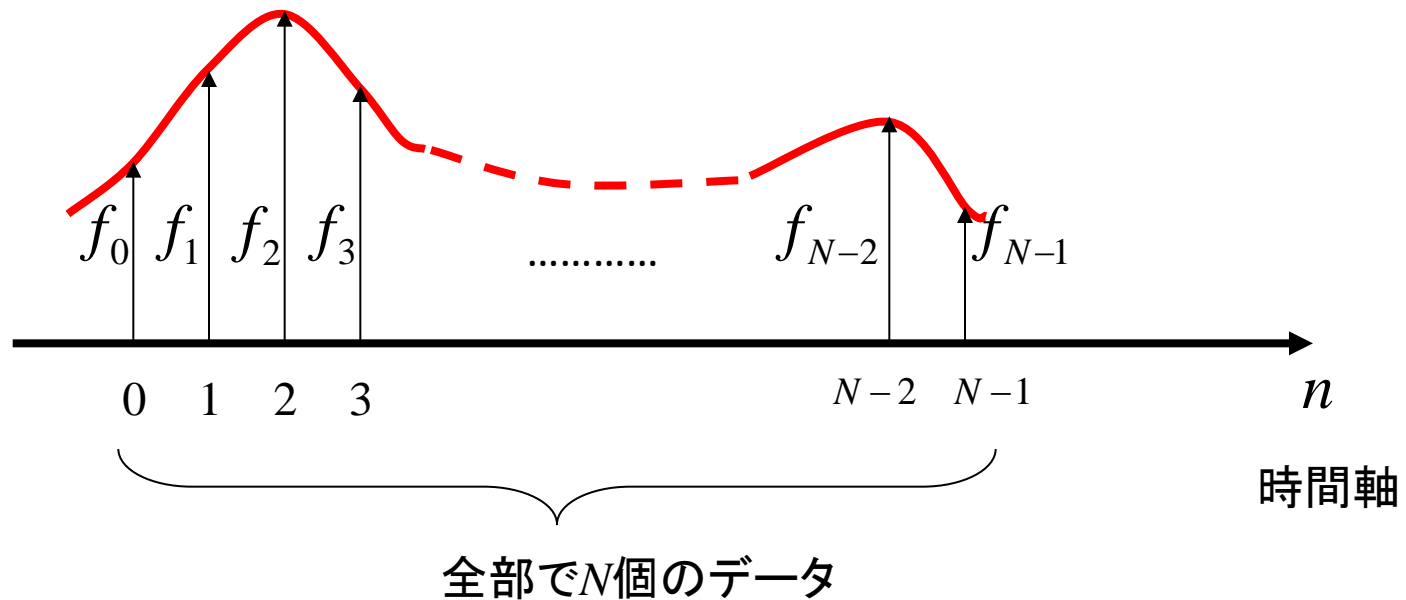
- ある信号の周波数成分を求める方法

$$y(t) = \sin(2\pi f_1 t)$$



フーリエ変換によって求まるパワースペクトル

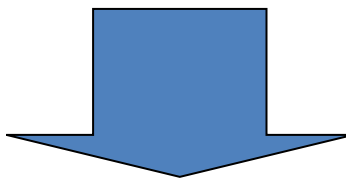
# 1次元離散的フーリエ変換



定義:

$$F_k = \sum_{n=0}^{N-1} f_n W_N^{nk} \quad W_N = e^{-j\frac{2\pi}{N}}$$
$$= \cos\left(\frac{2\pi}{N}\right) - j \sin\left(\frac{2\pi}{N}\right)$$

$$\begin{bmatrix} F_0 \\ F_1 \\ F_2 \\ F_3 \\ F_4 \\ F_5 \\ F_6 \\ F_7 \end{bmatrix} = \begin{bmatrix} W_8^0 & W_8^0 & W_8^0 & W_8^0 & W_8^0 & W_8^0 & W_8^0 & W_8^0 \\ W_8^0 & W_8^1 & W_8^2 & W_8^3 & W_8^4 & W_8^5 & W_8^6 & W_8^7 \\ W_8^0 & W_8^2 & W_8^4 & W_8^6 & W_8^8 & W_8^{10} & W_8^{12} & W_8^{14} \\ W_8^0 & W_8^3 & W_8^6 & W_8^9 & W_8^{12} & W_8^{15} & W_8^{18} & W_8^{21} \\ W_8^0 & W_8^4 & W_8^8 & W_8^{12} & W_8^{16} & W_8^{20} & W_8^{24} & W_8^{28} \\ W_8^0 & W_8^5 & W_8^{10} & W_8^{15} & W_8^{20} & W_8^{25} & W_8^{30} & W_8^{35} \\ W_8^0 & W_8^6 & W_8^{12} & W_8^{18} & W_8^{24} & W_8^{30} & W_8^{36} & W_8^{42} \\ W_8^0 & W_8^7 & W_8^{14} & W_8^{21} & W_8^{28} & W_8^{35} & W_8^{42} & W_8^{49} \end{bmatrix} \begin{bmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \\ f_7 \end{bmatrix}$$

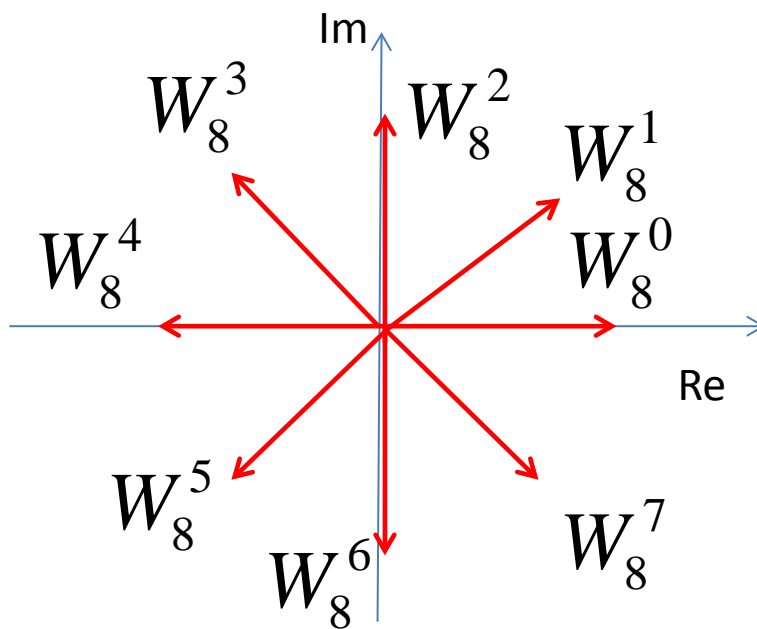


8 × 8 = 64回の乗算が必要

一般には高速フーリエ変換が利用される

# 回転子 $W$

例えば  $W_8^{49} = W_8^9 = W_8^{2+7}$  と表記できる



# 奇数と偶数に並び替え

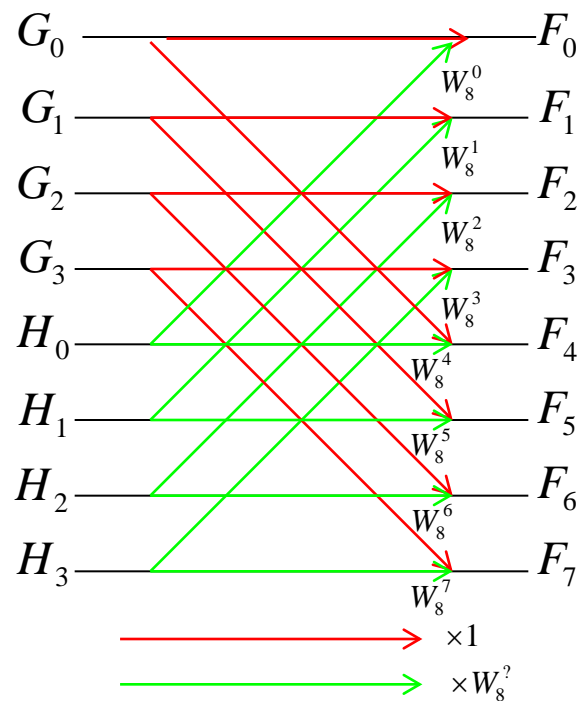
$$\begin{bmatrix} F_0 \\ F_1 \\ F_2 \\ F_3 \\ F_4 \\ F_5 \\ F_6 \\ F_7 \end{bmatrix} = \begin{bmatrix} W_8^0 & W_8^0 & W_8^0 & W_8^0 & W_8^{0+0} & W_8^{0+0} & W_8^{0+0} & W_8^{0+0} \\ W_8^0 & W_8^2 & W_8^4 & W_8^6 & W_8^{0+1} & W_8^{2+1} & W_8^{4+1} & W_8^{6+1} \\ W_8^0 & W_8^4 & W_8^0 & W_8^4 & W_8^{0+2} & W_8^{4+2} & W_8^{0+2} & W_8^{4+2} \\ W_8^0 & W_8^6 & W_8^4 & W_8^2 & W_8^{0+3} & W_8^{6+3} & W_8^{4+3} & W_8^{2+3} \\ \hline W_8^0 & W_8^0 & W_8^0 & W_8^0 & W_8^{0+4} & W_8^{0+4} & W_8^{0+4} & W_8^{0+4} \\ W_8^0 & W_8^2 & W_8^4 & W_8^6 & W_8^{0+5} & W_8^{2+5} & W_8^{4+5} & W_8^{6+5} \\ W_8^0 & W_8^4 & W_8^0 & W_8^4 & W_8^{0+6} & W_8^{4+6} & W_8^{0+6} & W_8^{4+6} \\ W_8^0 & W_8^6 & W_8^4 & W_8^2 & W_8^{0+7} & W_8^{6+7} & W_8^{4+7} & W_8^{2+7} \end{bmatrix} \begin{bmatrix} f_0 \\ f_2 \\ f_4 \\ f_6 \\ f_1 \\ f_3 \\ f_5 \\ f_7 \end{bmatrix}$$

# 時間間引き

# 4点のDFT

$$\begin{bmatrix} F_0 \\ F_1 \\ F_2 \\ F_3 \\ F_4 \\ F_5 \\ F_6 \\ F_7 \end{bmatrix} = \begin{bmatrix} (f_0W_8^0 + f_2W_8^0 + f_4W_8^0 + f_6W_8^0) + (f_1W_8^0 + f_3W_8^0 + f_5W_8^0 + f_7W_8^0)W_8^0 \\ (f_0W_8^0 + f_2W_8^2 + f_4W_8^4 + f_6W_8^6) + (f_1W_8^0 + f_3W_8^2 + f_5W_8^4 + f_7W_8^6)W_8^1 \\ (f_0W_8^0 + f_2W_8^4 + f_4W_8^0 + f_6W_8^4) + (f_1W_8^0 + f_3W_8^4 + f_5W_8^0 + f_7W_8^4)W_8^2 \\ (f_0W_8^0 + f_2W_8^6 + f_4W_8^4 + f_6W_8^2) + (f_1W_8^0 + f_3W_8^6 + f_5W_8^4 + f_7W_8^2)W_8^3 \\ (f_0W_8^0 + f_2W_8^0 + f_4W_8^0 + f_6W_8^0) + (f_1W_8^0 + f_3W_8^0 + f_5W_8^0 + f_7W_8^0)W_8^4 \\ (f_0W_8^0 + f_2W_8^2 + f_4W_8^4 + f_6W_8^6) + (f_1W_8^0 + f_3W_8^2 + f_5W_8^4 + f_7W_8^6)W_8^5 \\ (f_0W_8^0 + f_2W_8^6 + f_4W_8^4 + f_6W_8^2) + (f_1W_8^0 + f_3W_8^6 + f_5W_8^4 + f_7W_8^2)W_8^6 \\ (f_0W_8^0 + f_2W_8^6 + f_4W_8^4 + f_6W_8^2) + (f_1W_8^0 + f_3W_8^6 + f_5W_8^4 + f_7W_8^2)W_8^7 \end{bmatrix}$$

$$\begin{bmatrix} F_0 \\ F_1 \\ F_2 \\ F_3 \\ F_4 \\ F_5 \\ F_6 \\ F_7 \end{bmatrix} = \begin{bmatrix} G_0 + H_0W_8^0 \\ G_1 + H_1W_8^1 \\ G_2 + H_2W_8^2 \\ G_3 + H_3W_8^3 \\ G_0 + H_0W_8^4 \\ G_1 + H_1W_8^5 \\ G_2 + H_2W_8^6 \\ G_3 + H_3W_8^7 \end{bmatrix}$$



# 奇数行と偶数行に分ける

$$\begin{bmatrix} G_0 \\ G_1 \\ G_2 \\ G_3 \end{bmatrix} = \begin{bmatrix} W_8^0 & W_8^0 & W_8^0 & W_8^0 \\ W_8^0 & W_8^2 & W_8^4 & W_8^6 \\ W_8^0 & W_8^4 & W_8^0 & W_8^4 \\ W_8^0 & W_8^6 & W_8^4 & W_8^2 \end{bmatrix} \begin{bmatrix} f_0 \\ f_2 \\ f_4 \\ f_6 \end{bmatrix} = \begin{bmatrix} W_4^0 & W_4^0 & W_4^0 & W_4^0 \\ W_4^0 & W_4^1 & W_4^2 & W_4^3 \\ W_4^0 & W_4^2 & W_4^0 & W_4^2 \\ W_4^0 & W_4^3 & W_4^2 & W_4^1 \end{bmatrix} \begin{bmatrix} f_0 \\ f_2 \\ f_4 \\ f_6 \end{bmatrix}$$

$$\begin{bmatrix} G_0 \\ G_1 \\ G_2 \\ G_3 \end{bmatrix} = \begin{bmatrix} W_4^0 & W_4^0 & W_4^0 & W_4^0 \\ W_4^0 & W_4^2 & W_4^1 & W_4^3 \\ W_4^0 & W_4^0 & W_4^2 & W_4^2 \\ W_4^0 & W_4^2 & W_4^3 & W_4^1 \end{bmatrix} \begin{bmatrix} f_0 \\ f_4 \\ f_2 \\ f_6 \end{bmatrix} = \begin{bmatrix} W_4^0 & W_4^0 & W_4^{0+0} & W_4^{0+0} \\ W_4^0 & W_4^2 & W_4^{0+1} & W_4^{2+1} \\ \hline W_4^0 & W_4^0 & W_4^{0+2} & W_4^{0+2} \\ W_4^0 & W_4^2 & W_4^{0+3} & W_4^{2+3} \end{bmatrix} \begin{bmatrix} f_0 \\ f_4 \\ f_2 \\ f_6 \end{bmatrix}$$

$$\begin{bmatrix} G_0 \\ G_1 \\ G_2 \\ G_3 \end{bmatrix} = \begin{bmatrix} (f_0 W_4^0 + f_4 W_4^0) + (f_2 W_4^0 + f_6 W_4^0) W_4^0 \\ (f_0 W_4^0 + f_4 W_4^2) + (f_2 W_4^0 + f_6 W_4^2) W_4^1 \\ \hline (f_0 W_4^0 + f_4 W_4^0) + (f_2 W_4^0 + f_6 W_4^0) W_4^2 \\ (f_0 W_4^0 + f_4 W_4^2) + (f_2 W_4^0 + f_6 W_4^2) W_4^3 \end{bmatrix} = \begin{bmatrix} (f_0 W_2^0 + f_4 W_2^0) + (f_2 W_2^0 + f_6 W_2^0) W_4^0 \\ (f_0 W_2^0 + f_4 W_2^1) + (f_2 W_2^0 + f_6 W_2^1) W_4^1 \\ \hline (f_0 W_2^0 + f_4 W_2^0) + (f_2 W_2^0 + f_6 W_2^0) W_4^2 \\ (f_0 W_2^0 + f_4 W_2^1) + (f_2 W_2^0 + f_6 W_2^1) W_4^3 \end{bmatrix}$$

$$= \begin{bmatrix} J_0 + K_0 W_4^0 \\ J_1 + K_1 W_4^1 \\ \hline J_0 + K_0 W_4^2 \\ J_1 + K_1 W_4^3 \end{bmatrix}$$



# 奇数行と偶数行に分ける

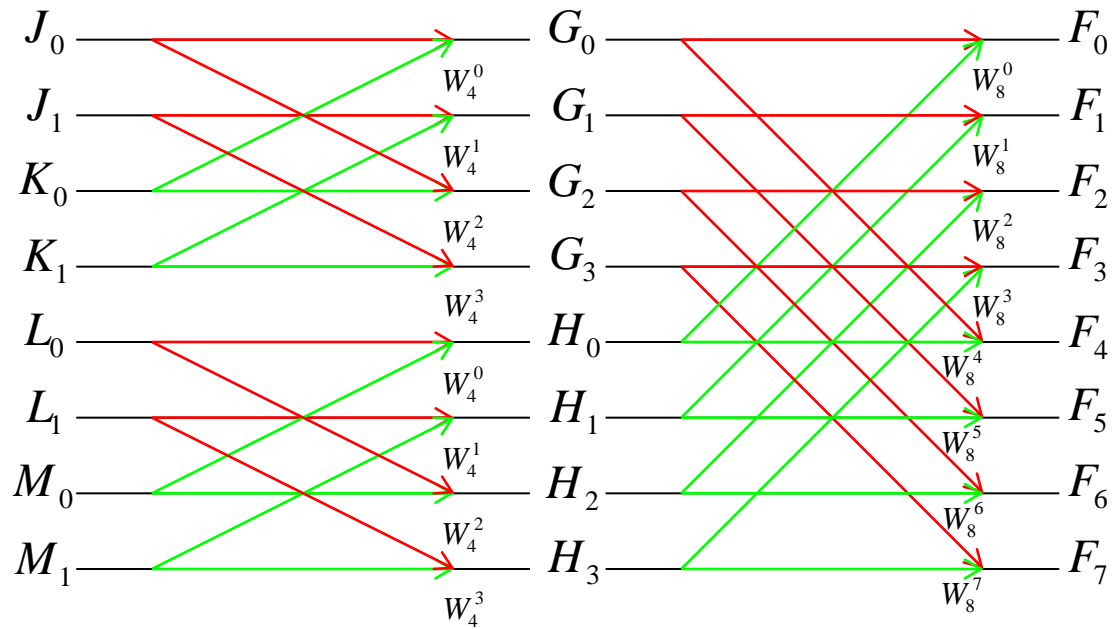
$$\begin{bmatrix} H_0 \\ H_1 \\ H_2 \\ H_3 \end{bmatrix} = \begin{bmatrix} W_8^0 & W_8^0 & W_8^0 & W_8^0 \\ W_8^0 & W_8^2 & W_8^4 & W_8^6 \\ W_8^0 & W_8^4 & W_8^0 & W_8^4 \\ W_8^0 & W_8^6 & W_8^4 & W_8^2 \end{bmatrix} \begin{bmatrix} f_1 \\ f_3 \\ f_5 \\ f_7 \end{bmatrix} = \begin{bmatrix} W_4^0 & W_4^0 & W_4^0 & W_4^0 \\ W_4^0 & W_4^1 & W_4^2 & W_4^3 \\ W_4^0 & W_4^2 & W_4^0 & W_4^2 \\ W_4^0 & W_4^3 & W_4^2 & W_4^1 \end{bmatrix} \begin{bmatrix} f_1 \\ f_3 \\ f_5 \\ f_7 \end{bmatrix}$$

$$\begin{bmatrix} H_0 \\ H_1 \\ H_2 \\ H_3 \end{bmatrix} = \begin{bmatrix} W_4^0 & W_4^0 & W_4^0 & W_4^0 \\ W_4^0 & W_4^2 & W_4^1 & W_4^3 \\ W_4^0 & W_4^0 & W_4^2 & W_4^2 \\ W_4^0 & W_4^2 & W_4^3 & W_4^1 \end{bmatrix} \begin{bmatrix} f_1 \\ f_5 \\ f_3 \\ f_7 \end{bmatrix} = \begin{bmatrix} W_4^0 & W_4^0 & W_4^{0+0} & W_4^{0+0} \\ W_4^0 & W_4^2 & W_4^{0+1} & W_4^{2+1} \\ W_4^0 & W_4^0 & W_4^{0+2} & W_4^{0+2} \\ W_4^0 & W_4^2 & W_4^{0+3} & W_4^{2+3} \end{bmatrix} \begin{bmatrix} f_1 \\ f_5 \\ f_3 \\ f_7 \end{bmatrix}$$

$$\begin{bmatrix} H_0 \\ H_1 \\ H_2 \\ H_3 \end{bmatrix} = \begin{bmatrix} (f_1 W_4^0 + f_5 W_4^0) + (f_3 W_4^0 + f_7 W_4^0) W_4^0 \\ (f_1 W_4^0 + f_5 W_4^2) + (f_3 W_4^0 + f_7 W_4^2) W_4^1 \\ (f_1 W_4^0 + f_5 W_4^0) + (f_3 W_4^0 + f_7 W_4^0) W_4^2 \\ (f_1 W_4^0 + f_5 W_4^2) + (f_3 W_4^0 + f_7 W_4^2) W_4^3 \end{bmatrix} = \begin{bmatrix} (f_1 W_2^0 + f_5 W_2^0) + (f_3 W_2^0 + f_7 W_2^0) W_4^0 \\ (f_1 W_2^0 + f_5 W_2^1) + (f_3 W_2^0 + f_7 W_2^1) W_4^1 \\ (f_1 W_2^0 + f_5 W_2^0) + (f_3 W_2^0 + f_7 W_2^0) W_4^2 \\ (f_1 W_2^0 + f_5 W_2^1) + (f_3 W_2^0 + f_7 W_2^1) W_4^3 \end{bmatrix}$$

$$= \begin{bmatrix} L_0 + M_0 W_4^0 \\ L_1 + M_1 W_4^1 \\ L_0 + M_0 W_4^2 \\ L_1 + M_1 W_4^3 \end{bmatrix}$$

# バタフライ演算



# N=2のDFT

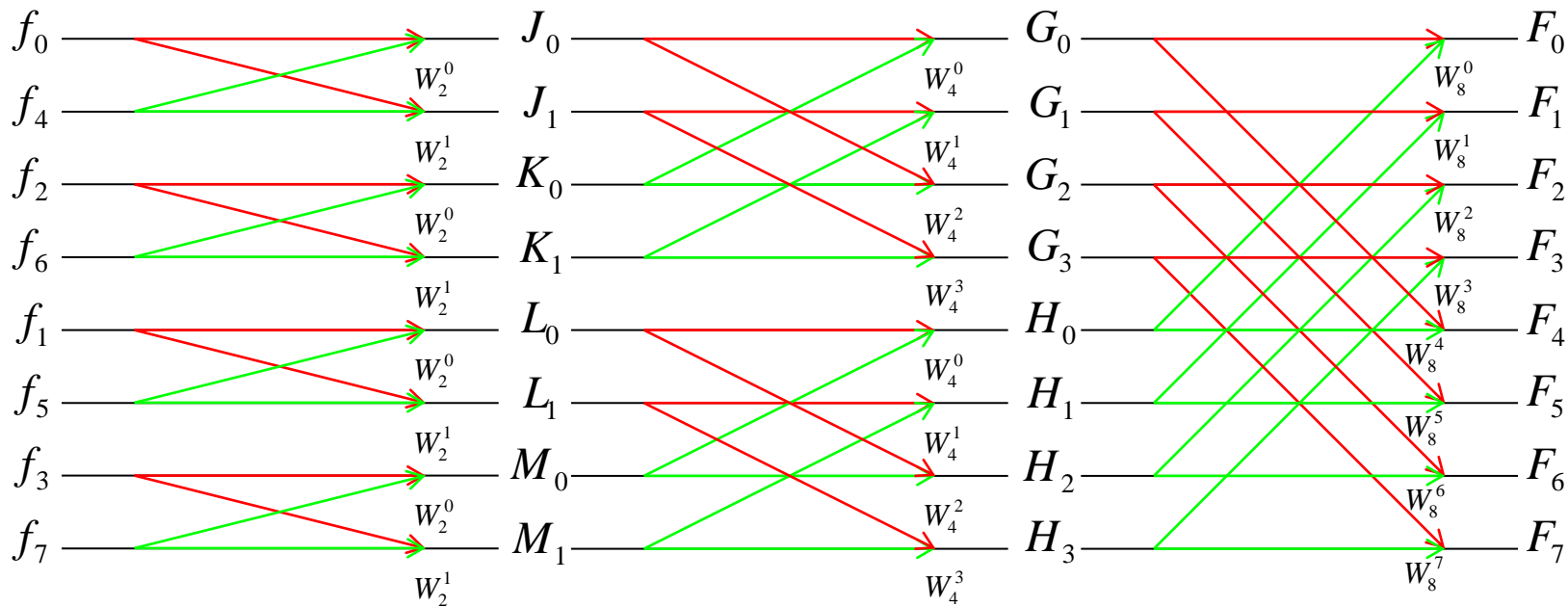
$$\begin{bmatrix} J_0 \\ J_1 \end{bmatrix} = \begin{bmatrix} W_4^0 & W_4^0 \\ W_4^0 & W_4^2 \end{bmatrix} \begin{bmatrix} f_0 \\ f_4 \end{bmatrix} = \begin{bmatrix} W_2^0 & W_2^0 \\ W_2^0 & W_2^1 \end{bmatrix} \begin{bmatrix} f_0 \\ f_4 \end{bmatrix}$$

$$\begin{bmatrix} K_0 \\ K_1 \end{bmatrix} = \begin{bmatrix} W_4^0 & W_4^0 \\ W_4^0 & W_4^2 \end{bmatrix} \begin{bmatrix} f_2 \\ f_6 \end{bmatrix} = \begin{bmatrix} W_2^0 & W_2^0 \\ W_2^0 & W_2^1 \end{bmatrix} \begin{bmatrix} f_2 \\ f_6 \end{bmatrix}$$

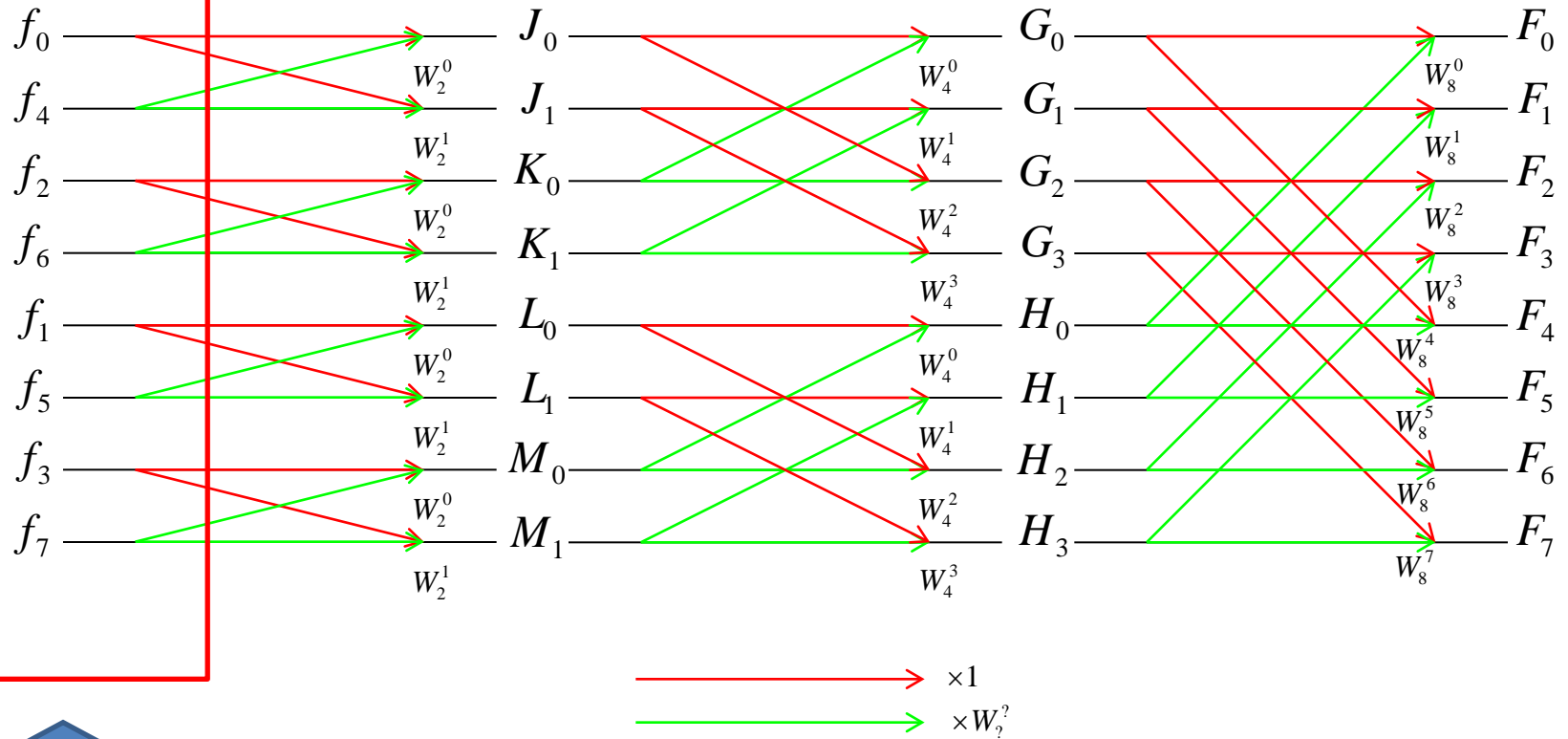
$$\begin{bmatrix} L_0 \\ L_1 \end{bmatrix} = \begin{bmatrix} W_4^0 & W_4^0 \\ W_4^0 & W_4^2 \end{bmatrix} \begin{bmatrix} f_1 \\ f_5 \end{bmatrix} = \begin{bmatrix} W_2^0 & W_2^0 \\ W_2^0 & W_2^1 \end{bmatrix} \begin{bmatrix} f_1 \\ f_5 \end{bmatrix}$$

$$\begin{bmatrix} M_0 \\ M_1 \end{bmatrix} = \begin{bmatrix} W_4^0 & W_4^0 \\ W_4^0 & W_4^2 \end{bmatrix} \begin{bmatrix} f_3 \\ f_7 \end{bmatrix} = \begin{bmatrix} W_2^0 & W_2^0 \\ W_2^0 & W_2^1 \end{bmatrix} \begin{bmatrix} f_3 \\ f_7 \end{bmatrix}$$

# バタフライ演算



# 全体の信号の流れ

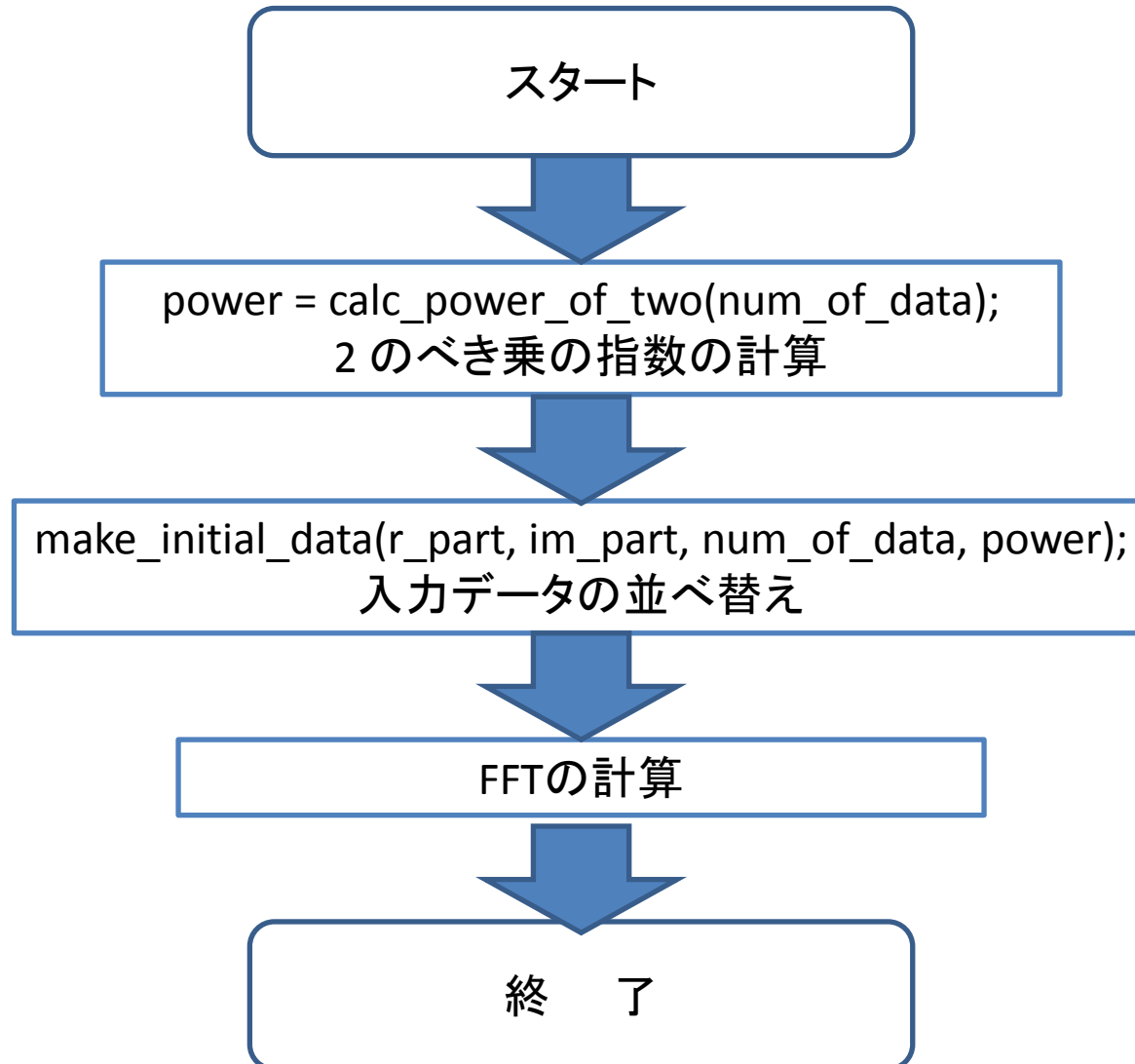


入力データをこの順番に並べ替えると演算がしやすくなる

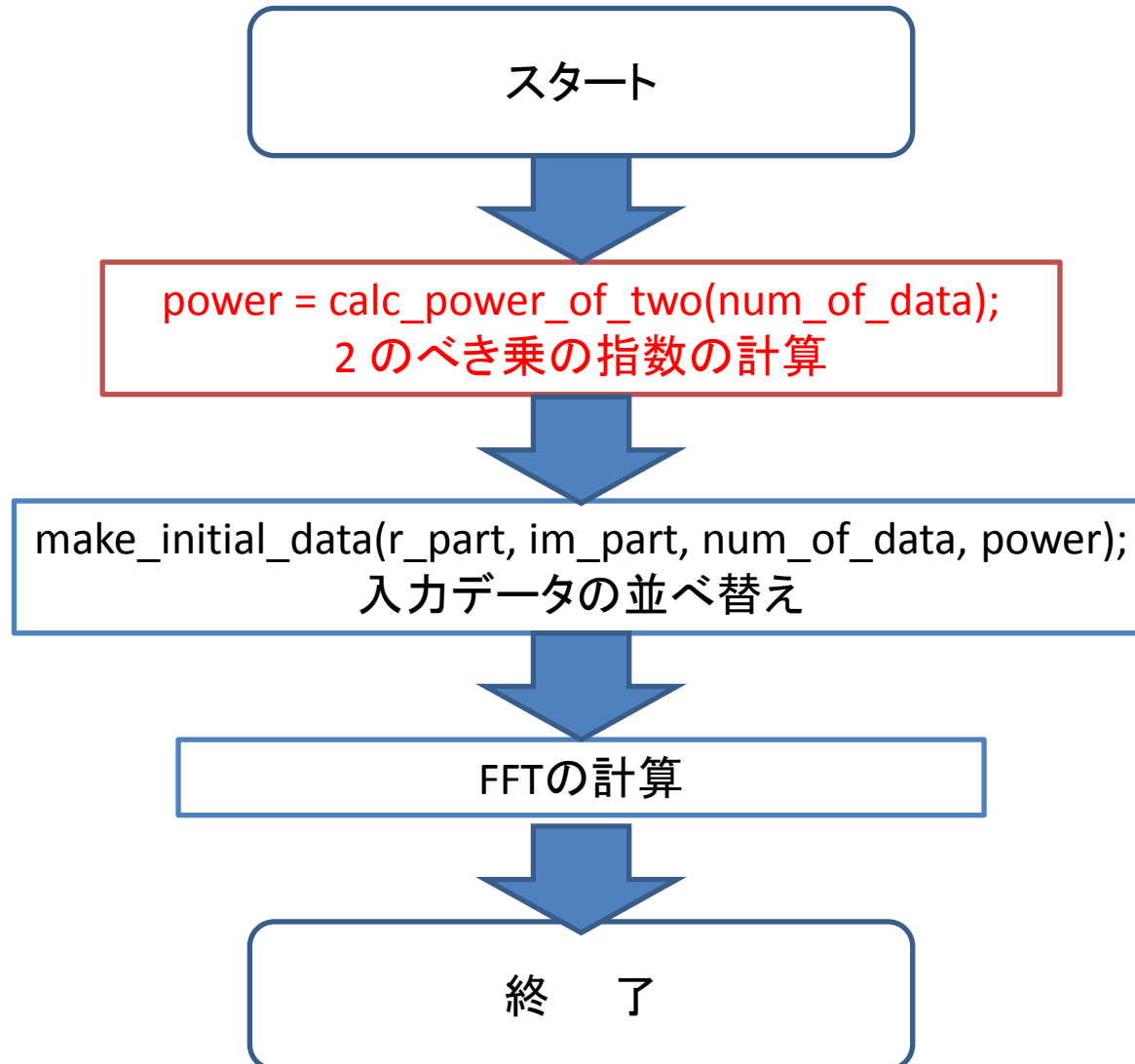
# 関数 FFT1の説明

- 1次元(例えば時系列データ)のFFTを計算する関数
- 引数
  - double \*r\_part : 入力データの実部
  - double \*im\_part : 入力データの虚部
  - int num\_of\_data : 入力データの数
  - int flag : 1であればFFT、-1であれば逆FFT

# 全体の流れ(順変換のみに着目)



# 全体の流れ(順変換のみに着目)





# 2のべき乗の指数の計算

```
int calc_power_of_two(int number)
{
    int power = 0;
    while (number != 1) {
        power++; number = number / 2
    }
    return (power);
}
```

例: number=8

```
int calc_power_of_two(8)
{
    int power = 0;
    while (8 != 1) {
        power++; number = number /2;
    }
    return (power);
}
```

例: number=8

```
int calc_power_of_two(8)
{
    int power = 0;
    while (8 != 1) {
        power=1; number = 4;
    }
    return (power);
}
```

例: number=8

```
int calc_power_of_two(8)
{
    int power = 0;
    while (4 != 1) {
        power=2; number = 2;
    }
    return (power);
}
```

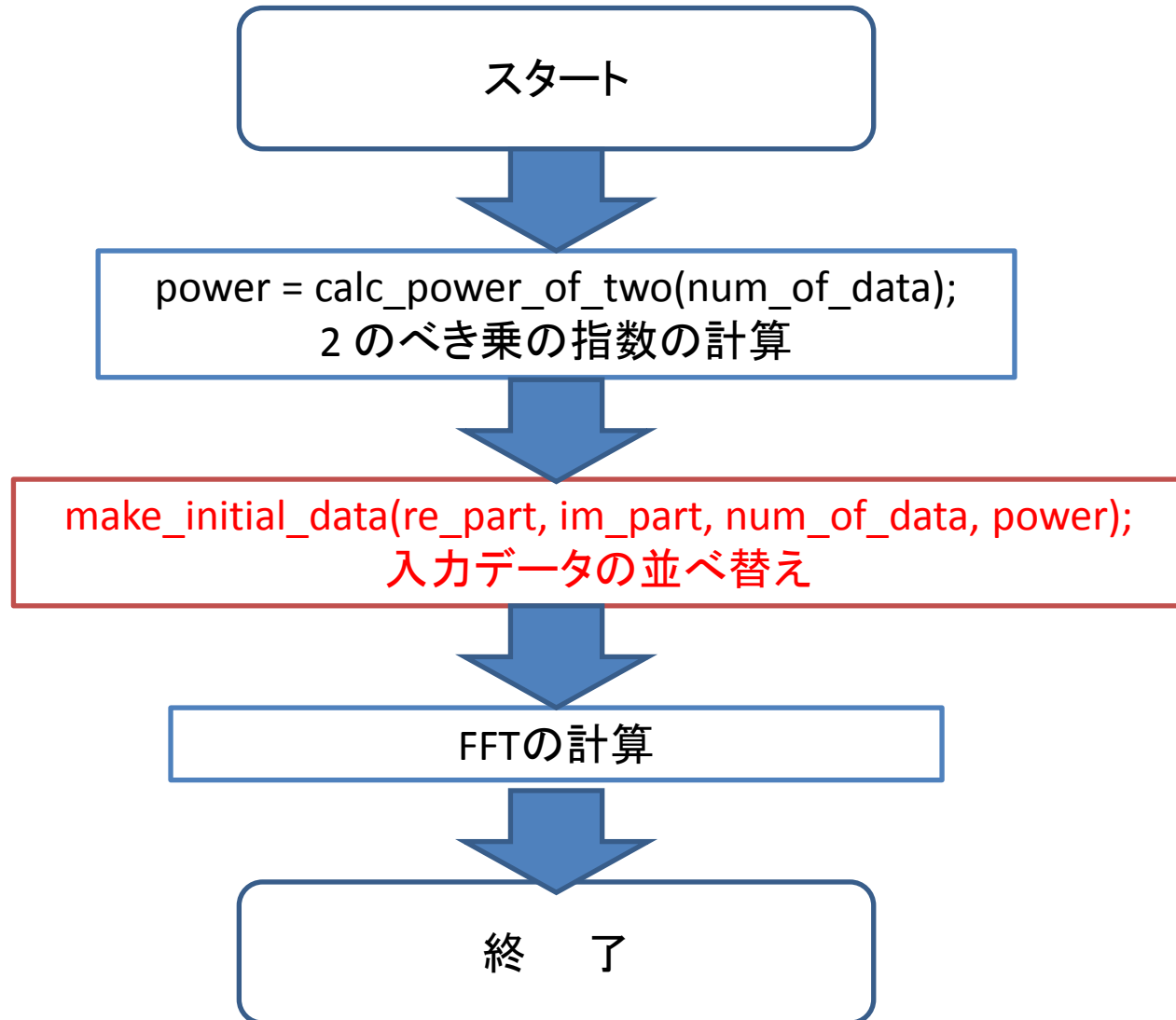
例: number=8

```
int calc_power_of_two(8)
{
    int power = 0;
    while (2 != 1) {
        power=3; number = 1;
    }
    return (power);
}
```

例: number=8=2<sup>3</sup>

```
int calc_power_of_two(8)
{
    int power = 0;
    while (1 != 1) {
        power=3; number = 1;
    }
    return (3);
}
```

# 全体の流れ(順変換のみに着目)



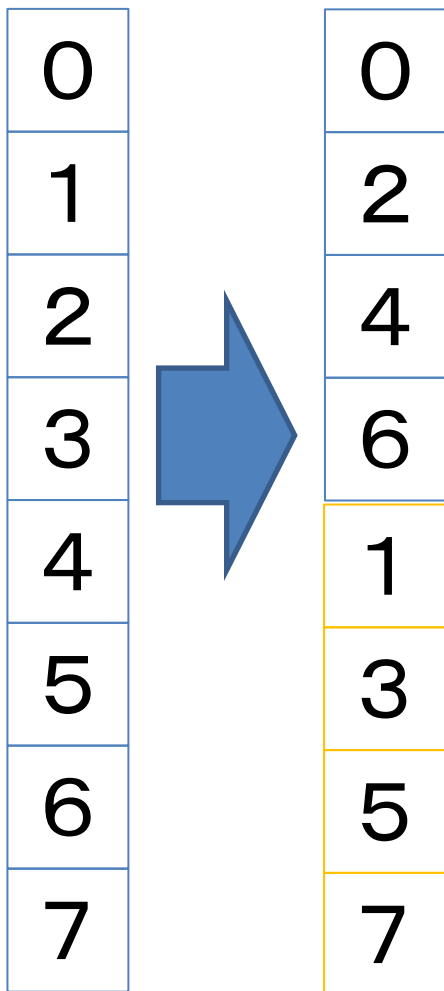
# 並べ替えアルゴリズム

奇数行と偶数行に分ける

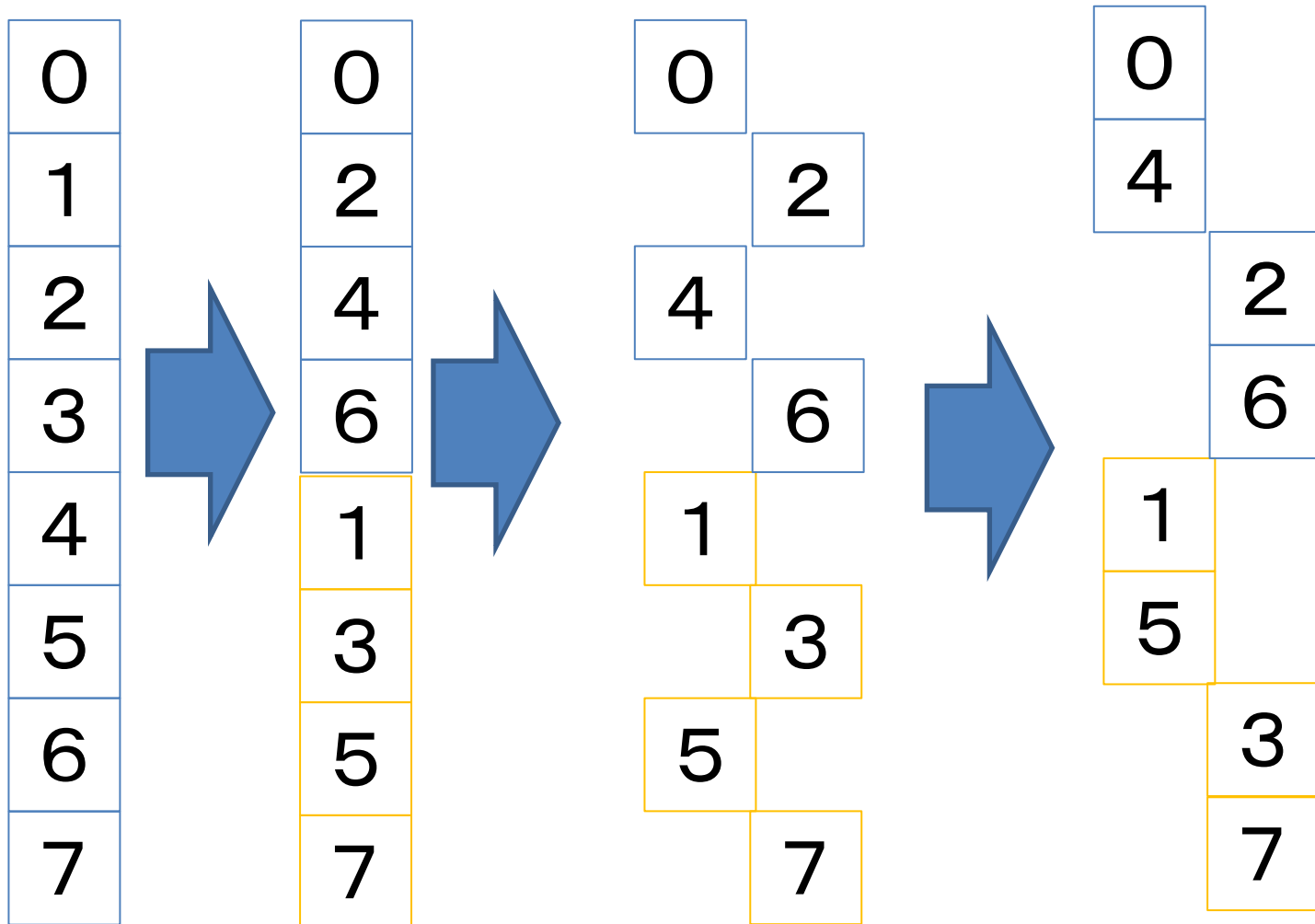
0
1
2
3
4
5
6
7



# 並べ替えアルゴリズム



# 並べ替えアルゴリズム



```
make_initial_data(double *r_part, double
                 *im_part, int num_of_data, int power)
```

```
dft= num of data;
```

```
for (i = 1; i < power; i++) {
```

```
    new_ptr = 0; offset = 0;
```

```
    while (new_ptr < num_of_data) {
```

```
        ptr = 0;
```

```
        while (ptr < dft) {
```

```
            re_buf[new_ptr] = *(re_part + offset + ptr);
```

```
            im_buf[new_ptr] = *(im_part + offset + ptr);
```

```
            new_ptr++;
```

```
            ptr = ptr + 2;
```

```
            if (ptr == dft) ptr = 1;
```

```
        }
```

```
        offset = offset + dft;
```

```
    } /* result of calculation is copied into arrays */
```

```
    for (j = 0; j < num_of_data; j++) {
```

```
        *(re_part + j) = re_buf[j];
```

```
        *(im_part + j) = im_buf[j];
```

```
    }
```

```
    dft= dft/ 2;
```

```
}
```

三重ループ

このループについて

# make\_initial\_data関数の引数

- `make_initial_data(double *re_part, double *im_part, int num_of_data, int power)`
- `*re_part, *im_part`: 入力データの実部・虚部
- `num_of_data`: 入力データ数
- `power`: 2 のべき乗の指数( `num_of_data = 8` であれば3)

# 例：データ数 $\text{num\_of\_data}=8=2^3$

```
dft= num_of_data;
for (i = 1; i < power<i++>) {
    new_ptr = 0; offset = 0;
    while (new_ptr < num_of_data) {
        ptr = 0;
        while (ptr < DFT) {
            re_buf [new_ptr] = *(re_part + offset + ptr);
            re_buf [new_ptr] = *(im_part +offset + ptr);
            new_ptr++;
            ptr = ptr + 2;
            if (ptr == dft) ptr = 1;
        }
        offset = offset + dft;
    } /* result of calculation is copied into arrays */
    for (j = 0; j < num_of_data; j++) {
        *(re_part + j) = re_buf[j];
        *(im_part + j) = im_buf[j];
    }
    dft= dft/ 2;
}
```

calc\_power\_of\_two関数で既に求めている

# 例：データ数8

```
dft = num_of_data=8;
for (i = 1; i < 3; i++) {
  new_ptr = 0; offset = 0;
  while (0 < 8) {
    ptr = 0;
    while (0 < 8) {
      re_buf[0] = *(re_part + 0 + 0);
      im_buf[0] = *(im_part + 0 + 0);
      new_ptr = 1;
      ptr = 2;
      if (2 == 8) pntnr = 1;
    }
    offset = offset + dft;
  } /* result of calculation is copied into arrays */
  for (j = 0; j < num_of_data; j++) {
    *(re_part + j) = re_buf[j];
    *(im_part + j) = im_buf[j];
  }
  dft = dft / 2;
}
```

re\_part[0]と同意

re\_part

0	1	2	3	4	5	6	7
---	---	---	---	---	---	---	---

re\_buf

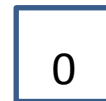
# 例：データ数8

```
dft = num_of_data=8;
for (i = 1; i < 3; i++) {
    new_ptr = 0; offset = 0;
    while (0 < 8) {
        ptr = 0;
        while (2 < 8) {
            re_buf[1] = *(re_part + 0 + 2);
            im_buf[1] = *(im_part + 0 + 2);
            new_ptr = 2;
            ptr = 4;
            if (4 == 8) ptr = 1;
        }
        offset = offset + dft;
    } /* result of calculation is copied into arrays */
    for (j = 0; j < num_of_data; j++) {
        *(re_part + j) = re_buf[j];
        *(im_part + j) = im_buf[j];
    }
    dft = dft / 2;
}
```

re\_part



re\_buf



# 例：データ数8

```
dft = num_of_data=8;
for (i = 1; i < 3; i++) {
  new_ptr = 0; offset = 0;
  while (0 < 8) {
    ptr = 0;
    while (4 < 8) {
      re_buf[2] = *(re_part + 0 + 4);
      im_buf[2] = *(im_part + 0 + 4);
      new_ptr = 3;
      ptr = 6;
      if (6 == 8) ptr = 1;
    }
    offset = offset + dft;
  } /* result of calculation is copied into arrays */
  for (j = 0; j < num_of_data; j++) {
    *(re_part + j) = re_buf[j];
    *(im_part + j) = im_buf[j];
  }
  dft = dft / 2;
}
```

re\_part



re\_buf





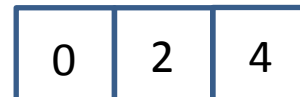
# 例：データ数8

```
dft = num_of_data=8;
for (i = 1; i < 3; i++) {
  new_ptr = 0; offset = 0;
  while (0 < 8) {
    ptr = 0;
    while (6 < 8) {
      re_buf[3] = *(re_part + 0 + 6);
      im_buf[3] = *(im_part + 0 + 6);
      new_ptr = 4;
      ptr = 8;
      if (8 == 8) ptr = 1;
    }
    offset = offset + dft;
  } /* result of calculation is copied into arrays */
  for (j = 0; j < num_of_data; j++) {
    *(re_part + j) = re_buf[j];
    *(im_part + j) = im_buf[j];
  }
  dft = dft / 2;
}
```

re\_part



re\_buf



# 例：データ数8

```
dft = num_of_data=8;
for (i = 1; i < 3; i++) {
    new_ptr = 0; offset = 0;
    while (0 < 8) {
        ptr = 0;
        while (1 < 8) {
            re_buf[4] = *(re_part + 0 + 1);
            im_buf[4] = *(im_part + 0 + 1);
            new_ptr = 5;
            ptr = 3;
            if (3 == 8) ptr = 1;
        }
        offset = offset + dft;
    }
    for (j = 0; j < num_of_data; j++) {
        *(re_part + j) = re_buf[j];
        *(im_part + j) = im_buf[j];
    }
    dft = dft / 2;
}
```

re\_part



re\_buf



# 例：データ数8

```
dft = num_of_data=8;
for (i = 1; i < 3; i++) {
  new_ptr = 0; offset = 0;
  while (0 < 8) {
    ptr = 0;
    while (3 < 8) {
      re_buf[5] = *(re_part + 0 + 3);
      im_buf[5] = *(im_part + 0 + 3);
      new_ptr = 6;
      ptr = 5;
      if (5 == 8) ptr = 1;
    }
    offset = offset + dft;
  }
  for (j = 0; j < num_of_data; j++) {
    *(re_part + j) = re_buf[j];
    *(im_part + j) = im_buf[j];
  }
  dft = dft / 2;
}
```

re\_part



re\_buf



# 例：データ数8

```
dft = num_of_data=8;
for (i = 1; i < 3; i++) {
    new_ptr = 0; offset = 0;
    while (0 < 8) {
        ptr = 0;
        while (5 < 8) {
            re_buf[5] = *(re_part + 0 + 5);
            im_buf[5] = *(im_part + 0 + 5);
            new_ptr = 7;
            ptr = 7;
            if (7 == 8) ptr = 1;
        }
        offset = offset + dft;
    }
    for (j = 0; j < num_of_data; j++) {
        *(re_part + j) = re_buf[j];
        *(im_part + j) = im_buf[j];
    }
    dft = dft / 2;
}
```

re\_part



re\_buf



# 例：データ数8

```
dft = num_of_data=8;
for (i = 1; i < 3; i++) {
  new_ptr = 0; offset = 0;
  while (0 < 8) {
    ptr = 0;
    while (7 < 8) {
      re_buf[7] = *(re_part + 0 + 7);
      im_buf[7] = *(im_part + 0 + 7);
      new_ptr = 8;
      ptr = 9;
      if (9 == 8) ptr = 1;
    }
    offset = offset + dft;
  }
  for (j = 0; j < num_of_data; j++) {
    *(re_part + j) = re_buf[j];
    *(im_part + j) = im_buf[j];
  }
  dft = dft / 2;
}
```

re\_part

0	1	2	3	4	5	6	7
---	---	---	---	---	---	---	---

re\_buf

0	2	4	6	1	3	5
---	---	---	---	---	---	---

# 例：データ数8

```
dft = num_of_data=8;
for (i = 1; i < 3; i++) {
    new_ptr = 0; offset = 0;
    while (8 < 8) {
        ptr = 0;
        while (7 < 8) {
            re_buf[7] = *(re_part + 0 + 7);
            im_buf[7] = *(im_part + 0 + 7);
            new_ptr = 8;
            ptr = 9;
            if (9 == 8) ptr = 1;
        }
        offset = 8;
    }
    for (j = 0; j < num_of_data; j++) {
        *(re_part + j) = re_buf[j];
        *(im_part + j) = im_buf[j];
    }
    dft = dft / 2;
}
```

re\_part

0	1	2	3	4	5	6	7
---	---	---	---	---	---	---	---

re\_buf

0	2	4	6	1	3	5	7
---	---	---	---	---	---	---	---

# 例：データ数8

```
dft = num_of_data=8;
for (i = 1; i < 3; i++) {
    new_ptr = 0; offset = 0;
    while (8 < 8) {
        ptr = 0;
        while (7 < 8) {
            re_buf[7] = *(re_part + 0 + 7);
            im_buf[7] = *(im_part + 0 + 7);
            new_ptr = 8;
            ptr = 9;
            if (9 == 8) ptr = 1;
        }
        offset = 8;
    }
    for (j = 0; j < 8; j++) {
        *(re_part + j) = re_buf[j];
        *(im_part + j) = im_buf[j];
    }
    dft = 8 / 2; = 4;
}
```

re\_part

re\_buf

0	2	4	6	1	3	5	7
---	---	---	---	---	---	---	---

# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (0 < 8) {  
        ptr = 0;  
        while (0 < 4) {  
            re_buf[new_ptr] = *(re_part + offset + ptr);  
            im_buf[new_ptr] = *(im_part + offset + ptr);  
            new_ptr++;  
            ptr = ptr + 2;  
            if (ptr == dft) ptr = 1;  
        }  
        offset = offset + 4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft / 2;  
}
```

re\_part

0	2	4	6	1	3	5	7
---	---	---	---	---	---	---	---

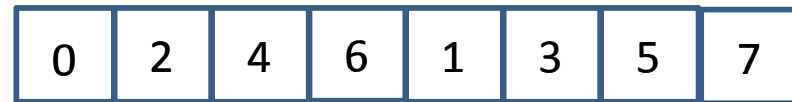
re\_buf



# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (0 < 8) {  
        ptr = 0;  
        while (0 < 4) {  
            re_buf[[0] = *(re_part + 0 + 0);  
            im_buf[[0] = *(im_part + 0 + 0);  
            new_ptr=1  
            ptr = 2  
            if (2 == 4) ptr = 1;  
        }  
        offset = 4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft/2  
}
```

re\_part

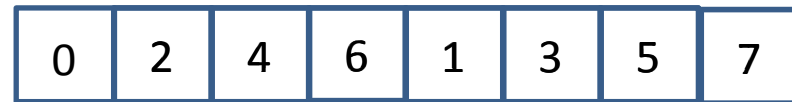


re\_buf

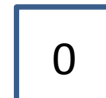
# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (0 < 8) {  
        ptr = 0;  
        while (2 < 4) {  
            re_buf[[1] = *(re_part + 0 + 2);  
            im_buf[[1] = *(im_part + 0 + 2);  
            new_ptr=2  
            ptr = 4  
            if (4 == 4) ptr = 1;  
        }  
        offset = 4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft/2  
}
```

re\_part



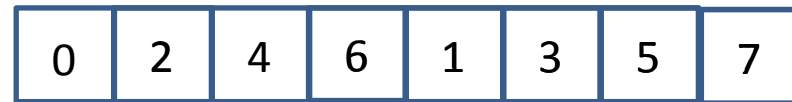
re\_buf



# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (0 < 8) {  
        ptr = 0;  
        while (1 < 4) {  
            re_buf[[2] = *(re_part + 0 + 1);  
            im_buf[[2] = *(im_part + 0 + 1);  
            new_ptr=3  
            ptr = 3  
            if (3 == 4) ptr = 1;  
        }  
        offset = 4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft/2  
}
```

re\_part



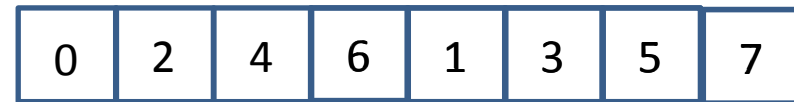
re\_buf



# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (0 < 8) {  
        ptr = 0;  
        while (3 < 4) {  
            re_buf[[3] = *(re_part + 0 + 3);  
            im_buf[[3] = *(im_part + 0 + 3);  
            new_ptr=4  
            ptr = 5  
            if (5 == 4) ptr = 1;  
        }  
        offset = offset+4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft/2  
}
```

re\_part



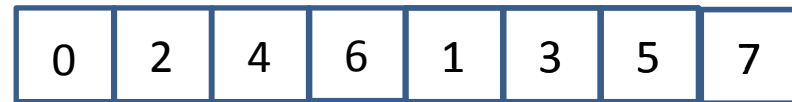
re\_buf



# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (4 < 8) {  
        ptr = 0;  
        while (3 < 4) {  
            re_buf[[3] = *(re_part + 0 + 3);  
            im_buf[[3] = *(im_part + 0 + 3);  
            new_ptr=4  
            ptr = 5  
            if (5 == 4) ptr = 1;  
        }  
        offset = offset+4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft/2  
}
```

re\_part



re\_buf



# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (4 < 8) {  
        ptr = 0;  
        while (0 < 4) {  
            re_buf[[4] = *(re_part + 4 + 0);  
            im_buf[[4] = *(im_part + 4 + 0);  
            new_ptr=5  
            ptr = 2  
            if (2 == 4) ptr = 1;  
        }  
        offset = offset+4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft/2  
}
```

re\_part



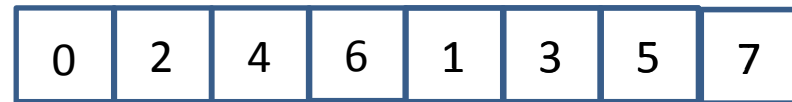
re\_buf



# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (4 < 8) {  
        ptr = 0;  
        while (0 < 4) {  
            re_buf[[4] = *(re_part + 4 + 0);  
            im_buf[[4] = *(im_part + 4 + 0);  
            new_ptr=5  
            ptr = 2  
            if (2 == 4) ptr = 1;  
        }  
        offset = offset+4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft/2  
}
```

re\_part



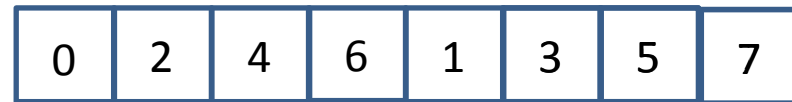
re\_buf



# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (4 < 8) {  
        ptr = 0;  
        while (2 < 4) {  
            re_buf[[5] = *(re_part + 4 + 2);  
            im_buf[[5] = *(im_part + 4 + 2);  
            new_ptr=6  
            ptr = 4  
            if (4 == 4) ptr = 1;  
        }  
        offset = offset+4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft/2  
}
```

re\_part



re\_buf





# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (4 < 8) {  
        ptr = 0;  
        while (1 < 4) {  
            re_buf[[6] = *(re_part + 4 + 1);  
            im_buf[[6] = *(im_part + 4 + 1);  
            new_ptr=7  
            ptr = 3  
            if (3 == 4) ptr = 1;  
        }  
        offset = offset+4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft/2  
}
```

re\_part



re\_buf



# 例：データ数8

```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (4 < 8) {  
        ptr = 0;  
        while (3 < 4) {  
            re_buf[[7] = *(re_part + 4 + 3);  
            im_buf[[7] = *(im_part + 4 + 3);  
            new_ptr=8  
            ptr = 5  
            if (5 == 4) ptr = 1;  
        }  
        offset = 4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = dft/2  
}
```

re\_part

0	2	4	6	1	3	5	7
---	---	---	---	---	---	---	---

re\_buf

0	4	2	6	1	5	3
---	---	---	---	---	---	---

# 例：データ数8

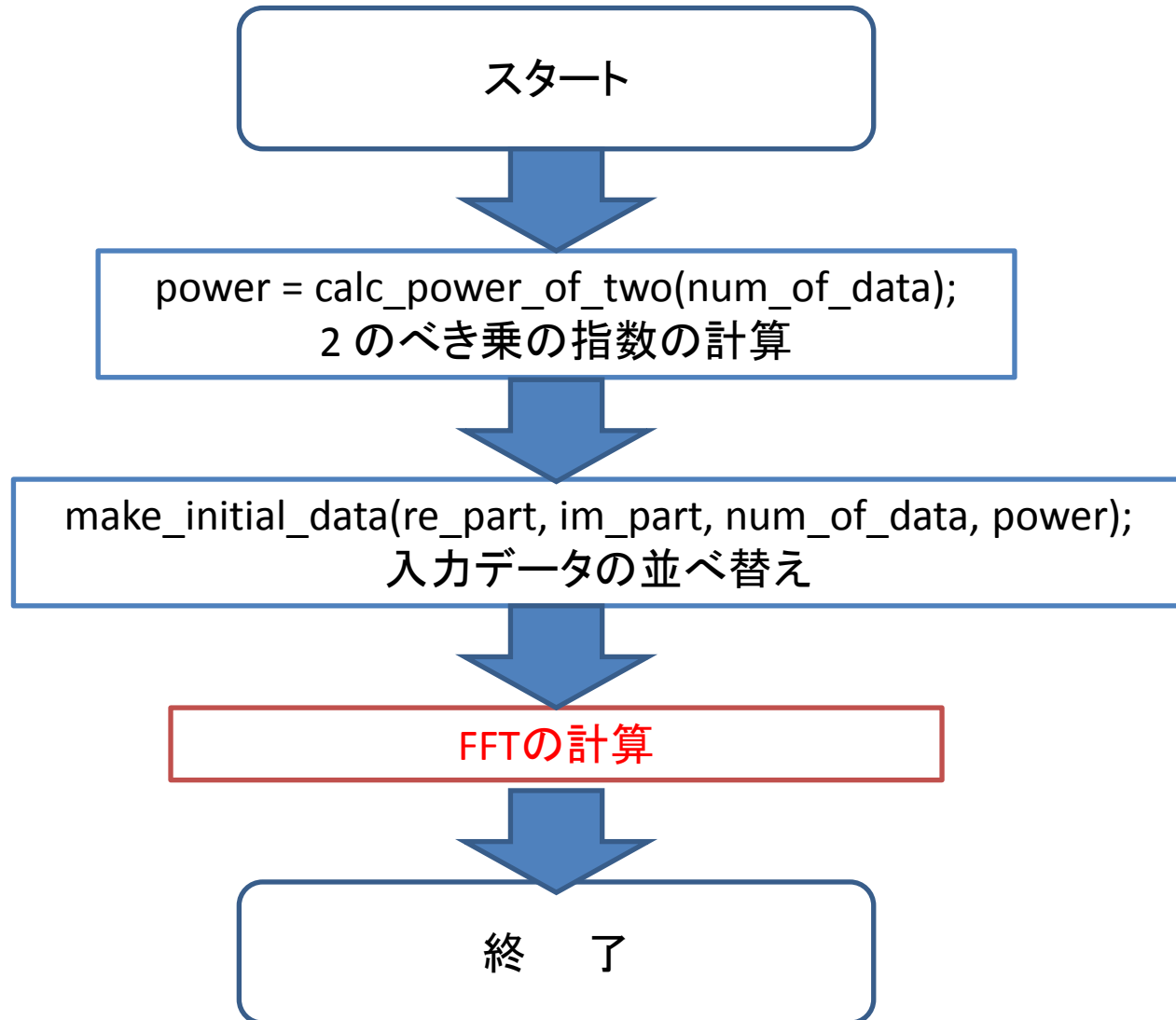
```
for (i = 2; i < 3; i++ i=2) {  
    new_ptr = 0; offset = 0;  
    while (8 < 8) {  
        ptr = 0;  
        while (5 < 4) {  
            re_buf[[7] = *(re_part + 4 + 3);  
            im_buf[[7] = *(im_part + 4 + 3);  
            new_ptr = 8;  
            ptr = 5;  
            if (5 == 4) ptr = 1;  
        }  
        offset = 4;  
    }  
    for (j = 0; j < num_of_data; j++) {  
        *(re_part + j) = re_buf[j];  
        *(im_part + j) = im_buf[j];  
    }  
    dft = 4/2 = 2;  
}
```

re\_part

re\_buf

0	4	2	6	1	5	3	7
---	---	---	---	---	---	---	---

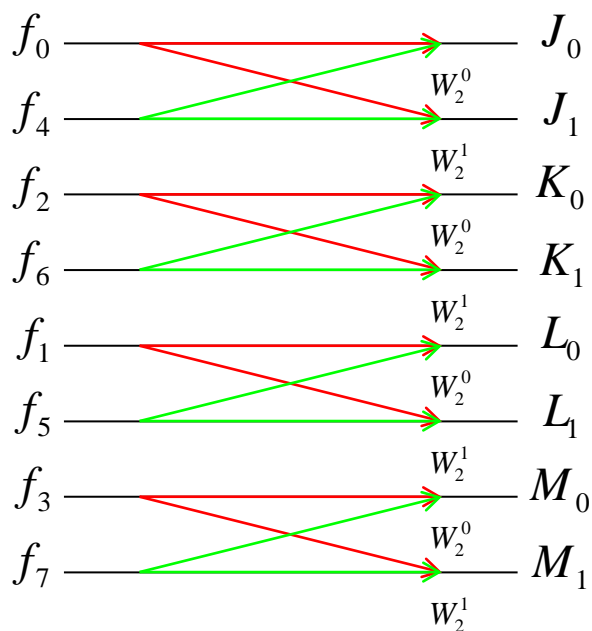
# 全体の流れ(順変換のみに着目)



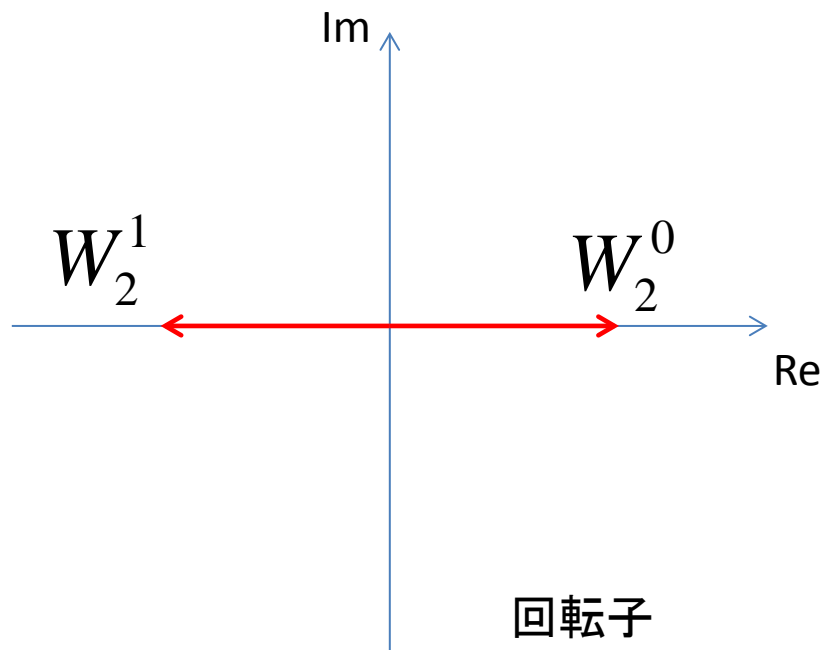
# ステップ1

$$W_N^k = e^{-j\frac{2\pi}{N}k}$$

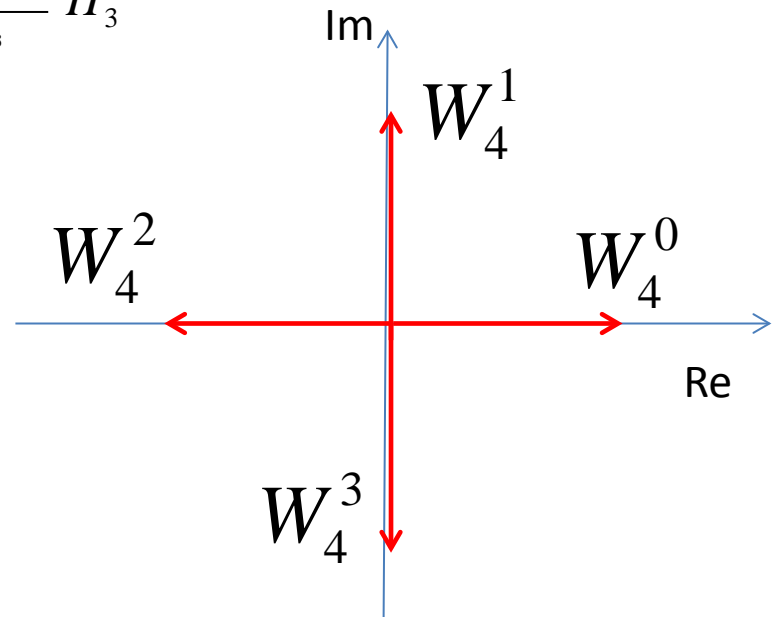
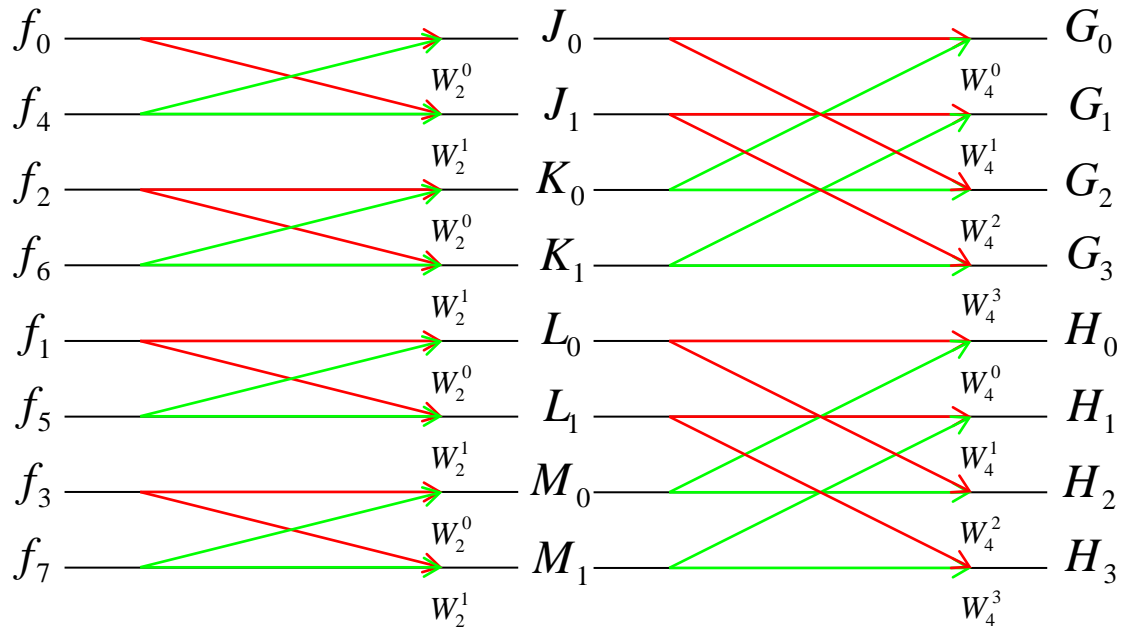
$$= \cos\left(\frac{2\pi}{N}k\right) - j\sin\left(\frac{2\pi}{N}k\right)$$



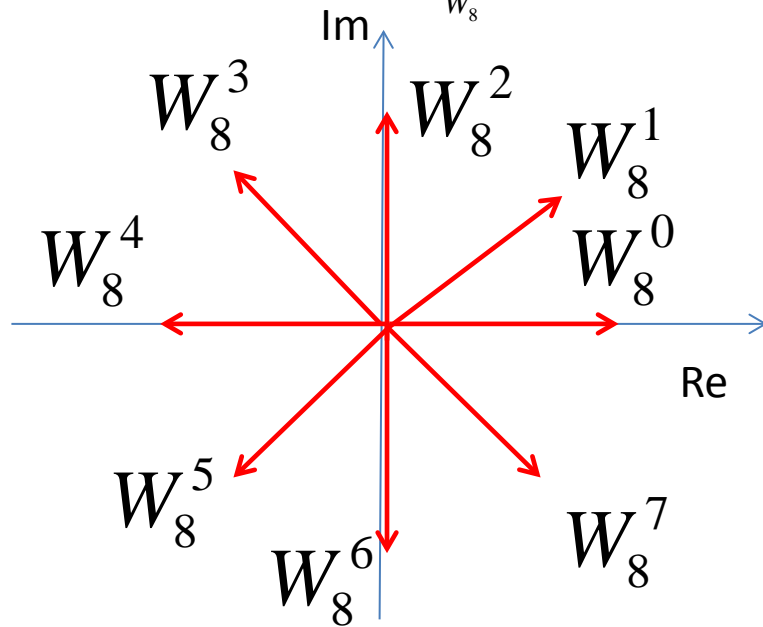
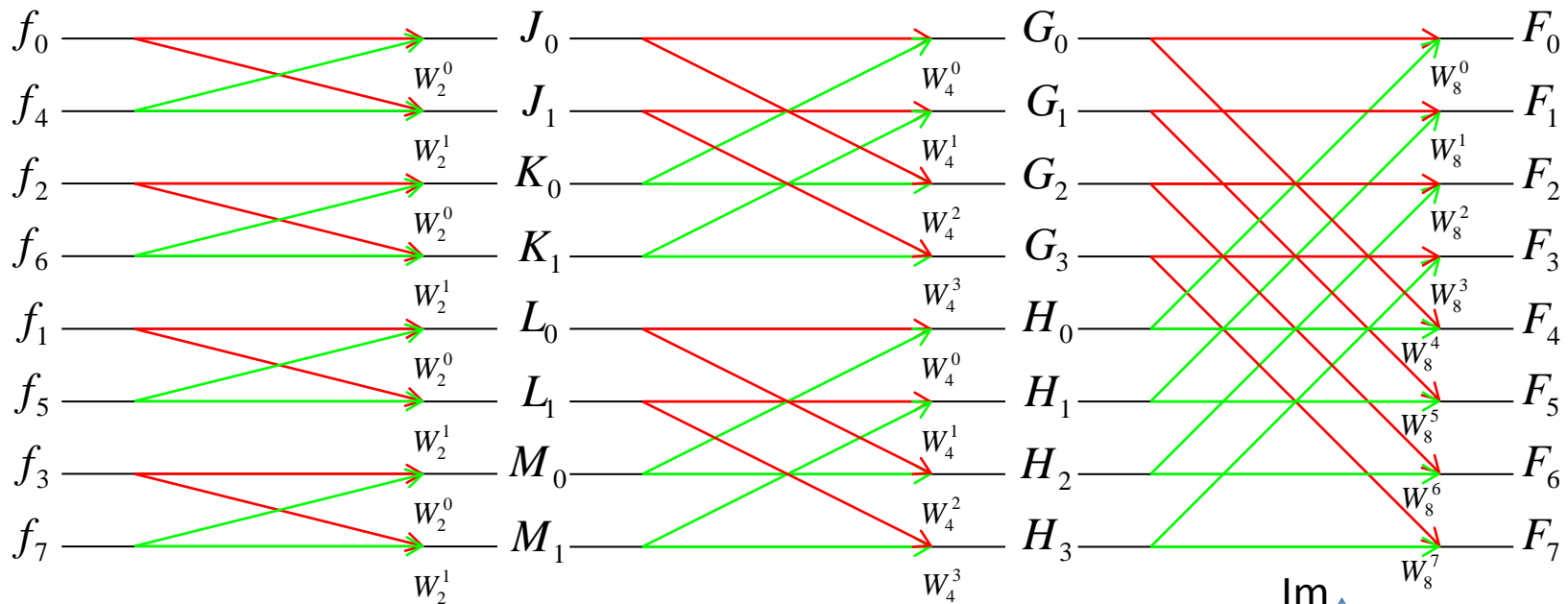
バタフライ



# ステップ2



# ステップ3



```
num_of_dft = num_of_data / dft;
step_angle = unit_angle * num_of_dft;
half = dft / 2;
for ( j = 0; j < num_of_dft; j ++ ){
    angle = 0.0;
    for ( k = 0; k < dft; k ++ ){
        num_out = j * dft + k;
        if ( k < half ){
            num_in1 = num_out;
            num_in2 = num_in1 + half;
        } else
        {
            num_in2 = num_out;
            num_in1 = num_out - half;
        }
    }
}
```

```
num_of_dft =  $8/2 = 4$ ;
step_angle =  $(2\pi/8) * 4 = \pi$ ;
half =  $2/2 = 1$ ;
for ( j = 0; j < 4; j ++ ){
    angle = 0.0;
    for ( k = 0; k < 2; k ++ ){
        num_out =  $0 * 2 + 0 = 0$ ;
        if ( k < 1 ){
            num_in1 = 0;
            num_in2 =  $0 + 1 = 1$ ;
        } else
        {
            num_in2 = num_out;
            num_in1 = num_out - half;
        }
    }
}
```



```

/* 実数部(re_)・虚数部(im_)に分けて計算 */
re_buf = *( re_part + num_in2 );
im_buf = *( im_part + num_in2 );
re_part_new[num_out] = *( re_part + num_in1 )
    + re_buf * cos(angle) + im_buf * sin(angle);
im_part_new[num_out] = *( im_part + num_in1 )
    + im_buf * cos(angle) - re_buf * sin(angle);
/* 角度を更新 */
angle = angle + step_angle;

```

```

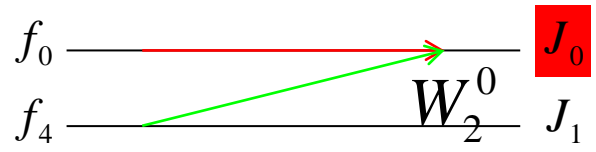
re_buf = *( re_part + 1);
im_buf = *( im_part + 1);
re_part_new[0] = *( re_part + 0)
    + re_buf * cos(0) + im_buf * sin(0);
im_part_new[0] = *( im_part + 0)
    + im_buf * cos(0) - re_buf * sin(0);

angle = angle + π = π;

```

$$J_0 = f_0 + ((re\_part) + j(im\_part)) * (\cos(0) - j \sin(0))$$

$J_0$  : re\_part\_new =  
 \*(re\_part+0) + \*(re\_part+1)\*cos(0) + \*(im\_part+1)\*sin(0)  
 \*(re\_part+0)  
 $J_0$  : im\_part\_new =  
 \*(im\_part+0) + \*(im\_part+1)\*cos(0) - \*(re\_part+1)\*sin(0)  
 \*(im\_part+0)



\*(re\_part+1)  
 \*(im\_part+1)

```
num_of_dft = num_of_data / dft;
step_angle = unit_angle * num_of_dft;
half = dft / 2;
for ( j = 0; j < num_of_dft; j ++ ){
    angle = 0.0;
    for ( k = 0; k < dft; k ++ ){
        num_out = j * dft + k;
        if ( k < half ){
            num_in1 = num_out;
            num_in2 = num_in1 + half;
        } else
        {
            num_in2 = num_out;
            num_in1 = num_out - half;
        }
    }
}
```

```
num_of_dft = 8/2 = 4;
step_angle = (2π/8)* 4 = π;
half = 2/ 2 = 1;
for ( j = 0; j < 4; j ++ ){
    angle = 0.0;
    for ( k = 0; k < 2; k ++ k=1){
        num_out = 0 * 2 + 1 = 1;
        if ( 1 < 1){
            num_in1 = num_out;
            num_in2 = num_in1 + half;
        } else
        {
            num_in2 = 1;
            num_in1 = 1 - 1=0;
        }
    }
}
```

```

/* 実数部(re_)・虚数部(im_)に分けて計算 */
re_buf = *( re_part + num_in2 );
im_buf = *( im_part + num_in2 );
re_part_new[num_out] = *( re_part + num_in1 )
    + re_buf * cos(angle) + im_buf * sin(angle);
im_part_new[num_out] = *( im_part + num_in1 )
    + im_buf * cos(angle) - re_buf * sin(angle);
/* 角度を更新 */
angle = angle + step_angle;

```

```

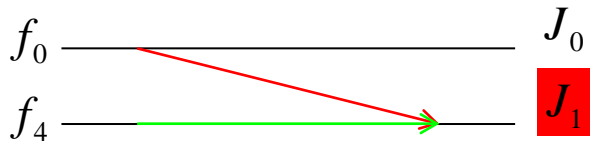
re_buf = *( re_part + 0);
im_buf = *( im_part + 0);
re_part_new[1] = *( re_part + 1)
    + re_buf * cos(π) + im_buf * sin(π);
im_part_new[1] = *( im_part + 1)
    + im_buf * cos(π) - re_buf * sin(π);

angle = angle + π = 2π;

```

$$J_1 = f_4 + ((re\_part) + j(im\_part)) * (\cos(0) - j \sin(0))$$

$J_1 : re\_part\_new =$   
 $*(re\_part+1) + *(re\_part+0) * \cos(\pi) + *(im\_part+0) * \sin(\pi)$   
 $*(re\_part+0)$   
 $J_1 : im\_part\_new =$   
 $*(im\_part+0) + *(im\_part+0) * \cos(\pi) - *(re\_part+0) * \sin(\pi)$   
 $*(im\_part+0)$



$*(re\_part+1)$   
 $*(im\_part+1)$

$W_2^1$

```
num_of_dft = num_of_data / dft;
step_angle = unit_angle * num_of_dft;
half = dft / 2;
for ( j = 0; j < num_of_dft; j ++ ){
    angle = 0.0;
    for ( k = 0; k < dft; k ++ ){
        num_out = j * dft + k;
        if ( k < half ){
            num_in1 = num_out;
            num_in2 = num_in1 + half;
        } else
        {
            num_in2 = num_out;
            num_in1 = num_out - half;
        }
    }
}
```

```
num_of_dft =  $8/4 = 2$ ;
step_angle =  $(2\pi/8) * 2 = \pi/2$ ;
half =  $4/2 = 2$ ;
for ( j = 0; j < 2; j ++ ){
    angle = 0.0;
    for ( k = 0; k < 4; k ++ k=0){
        num_out =  $0 * 4 + 0 = 0$ ;
        if (  $0 < 2$  ){
            num_in1 = 0;
            num_in2 =  $0 + 2 = 2$ ;
        } else
        {
            num_in2 = num_out;
            num_in1 = num_out - half;
        }
    }
}
```

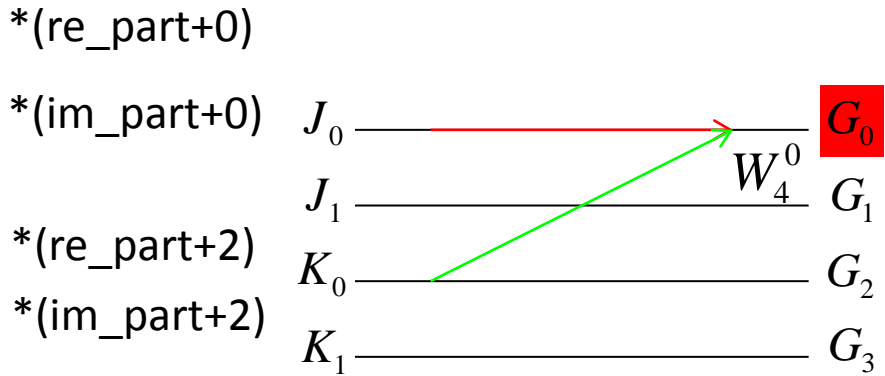
/\* 実数部(re\_)・虚数部(im\_)に分けて計算 \*/

```
re_buf = *( re_part + num_in2 );
im_buf = *( im_part + num_in2 );
re_part_new[num_out] = *( re_part + num_in1 )
    + re_buf * cos(angle) + im_buf * sin(angle);
im_part_new[num_out] = *( im_part + num_in1 )
    + im_buf * cos(angle) - re_buf * sin(angle);
```

```
/* 角度を更新 */
angle = angle + step_angle;
```

```
re_buf = *( re_part + 2);
im_buf = *( im_part + 2);
re_part_new[0] = *( re_part + 0)
    + re_buf * cos(0) + im_buf * sin(0);
im_part_new[0] = *( im_part + 0)
    + im_buf * cos(0) - re_buf * sin(0);
```

```
angle = angle +  $\pi$  / 2 =  $\pi$  / 2;
```



```
num_of_dft = num_of_data / dft;
step_angle = unit_angle * num_of_dft;
half = dft / 2;
for ( j = 0; j < num_of_dft; j ++ ){
    angle = 0.0;
    for ( k = 0; k < dft; k ++ ){
        num_out = j * dft + k;
        if ( k < half ){
            num_in1 = num_out;
            num_in2 = num_in1 + half;
        } else
        {
            num_in2 = num_out;
            num_in1 = num_out - half;
        }
    }
}
```

```
num_of_dft =  $8/4 = 2$ ;
step_angle =  $(2\pi/8) * 2 = \pi/2$ ;
half =  $4/2 = 2$ ;
for ( j = 0; j <  $2$ ; j ++ ){
    angle = 0.0;
    for ( k = 0; k < 4; k ++  $k=1$  ){
        num_out =  $0 * 4 + 1 = 1$ ;
        if (  $1 < 2$  ){
            num_in1 =  $1$ ;
            num_in2 =  $1 + 2 = 3$ ;
        } else
        {
            num_in2 = num_out;
            num_in1 = num_out - half;
        }
    }
}
```

```

/* 実数部(re_)・虚数部(im_)に分けて計算 */
re_buf = *( re_part + num_in2 );
im_buf = *( im_part + num_in2 );
re_part_new[num_out] = *( re_part + num_in1 )
    + re_buf * cos(angle) + im_buf * sin(angle);
im_part_new[num_out] = *( im_part + num_in1 )
    + im_buf * cos(angle) - re_buf * sin(angle);
/* 角度を更新 */
angle = angle + step_angle;

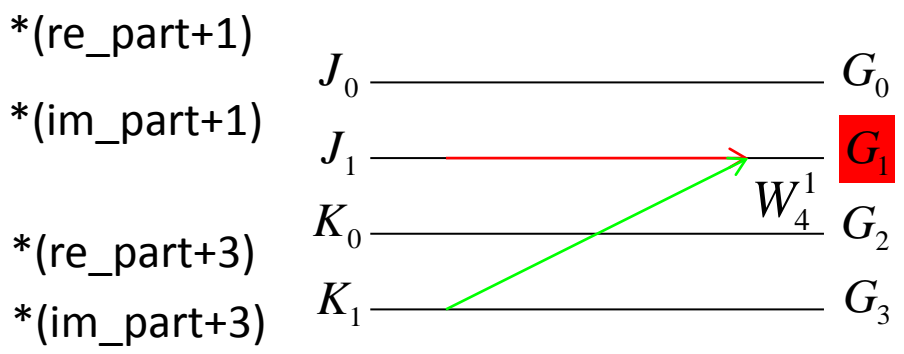
```

```

re_buf = *( re_part + 3);
im_buf = *( im_part + 3);
re_part_new[1] = *( re_part + 1)
    + re_buf * cos( $\pi/2$ ) + im_buf * sin( $\pi/2$ );
im_part_new[1] = *( im_part + 1)
    + im_buf * cos( $\pi/2$ ) - re_buf * sin( $\pi/2$ );

angle = angle +  $\pi / 2 = \pi$ ;

```



\*(re\_part+1)  
 \*(im\_part+1)  
 \*(re\_part+3)  
 \*(im\_part+3)

```
num_of_dft = num_of_data / dft;
step_angle = unit_angle * num_of_dft;
half = dft / 2;
for ( j = 0; j < num_of_dft; j ++ ){
    angle = 0.0;
    for ( k = 0; k < dft; k ++ ){
        num_out = j * dft + k;
        if ( k < half ){
            num_in1 = num_out;
            num_in2 = num_in1 + half;
        } else
        {
            num_in2 = num_out;
            num_in1 = num_out - half;
        }
    }
}
```

```
num_of_dft = 8/4 = 2;
step_angle = (2π/8)* 2 = π/2;
half = 4/ 2 = 2;
for ( j = 0; j < 2; j ++ ){
    angle = 0.0;
    for ( k = 0; k < 4; k ++ k=2){
        num_out = 0 * 4 + 2 = 2;
        if ( 2 < 2 ){
            num_in1 = num_out;
            num_in2 = num_in1 + half;
        } else
        {
            num_in2 = 2;
            num_in1 = 2 - 2 = 0;
        }
    }
}
```



```

/* 実数部(re_)・虚数部(im_)に分けて計算 */
re_buf = *( re_part + num_in2 );
im_buf = *( im_part + num_in2 );
re_part_new[num_out] = *( re_part + num_in1 )
    + re_buf * cos(angle) + im_buf * sin(angle);
im_part_new[num_out] = *( im_part + num_in1 )
    + im_buf * cos(angle) - re_buf * sin(angle);
/* 角度を更新 */
angle = angle + step_angle;

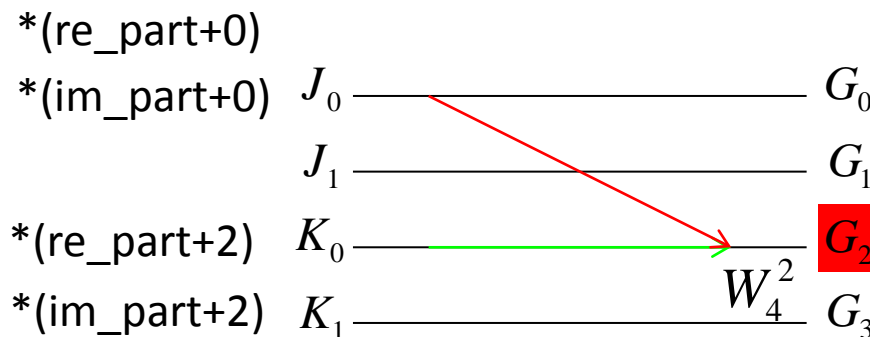
```

```

re_buf = *( re_part + 2);
im_buf = *( im_part + 2);
re_part_new[2] = *( re_part + 0)
    + re_buf * cos( $\pi$ ) + im_buf * sin( $\pi$ );
im_part_new[2] = *( im_part + 0)
    + im_buf * cos( $\pi$ ) - re_buf * sin( $\pi$ );

angle = angle +  $\pi / 2 = \pi$ ;

```



# 課題1

- 関数FFT1を利用して、1次元の時系列信号をフーリエ変換し、スペクトル表示せよ
  - 1次元の時系列信号は、複数の異なる周波数成分を持つ正弦波の和とする
  - スペクトルのグラフは表計算ソフトで表示して良い